## EPM50 Series Ø50mm Shaft Multi-Turn Absolute Type

## Diameter Ø50mm Shaft Type Absolute Multi-Turn Rotary Encoder

## Features

- Compact size of diameter Ø50mm
- Parallel data / SSI data transmission type
- Total 23bit resolution (8388608-division) of 10bit single-turn (1024-division) and 13bit multi-turn (8192-division)
- Easy zero adjustment using single-turn / multi-turn data separated reset function
- Memorizing revolution data up to ±90° after blackout without memory back up function
- Possible CW/CCW direction setting with direction function
- Maximizing users convenience with clear, overflow alarm (OVF) function
- Protection structure IP64 (IEC standard) (Dust-proof, Oil-proof)
- Provides Latch function (Parallel output model only)

## Applications

EPM50S

Series

Diameter

Ø50mm

Туре Model

specification

Electrical

Input

Resolution\*

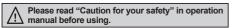
• Precision machine tool, Fabric machinery, Robot, Parking system

Single-turn

10bit

(1024-

division)



Ordering Information

Ø8mm

Specifications

Single-turn

Multi-turn

Output code

Output type

Output Line driver output

Logic

Response time

Input signal

Input level

Input logic

Input time

Output signal

Output Interface

NPN open collector output

Rotation limit when power is off \*2

Shaft diameter



R

Output code

Binary

Code

Ø50mm Multi-turn absolute encoder

SSI (Synchronous Serial Interface)

· Low: Sink current - Max. 20mA.

 High: Sink current - Max. -20mA, Output voltage - Min. 2.5VDC

High: 5-24VDC, Low: 0-1.2VDC

Single-turn data reset: Over 100ms Multi-turn count reset: Over 100ms

Direction: Over 100ms

Clear: Over 100ms No Latch function

Single-turn data, Multi-turn count, OVF alarm\*3

Residual voltage - Max. 0.5VDC

Single-turn data reset \*4, Multi-turn count reset

Low active \*6, HIGH or OPEN for common use

ΡN

PN: Parallel NPN open

collector output

Control output

S: SSI

13

Multi-turn

revolution)

EPM50S8-1013-B-S-24

1024-division (10Bit)

24bit, Binary 2 code

±90°

8192 revolution (13Bit)

13bit

(8192





Cable

No mark: Axial cable type

S: Radial cable type

24

Power supply

12-24VDC±5%

EPM50S8-1013-B-PN-24

NPN open collector output

Sink current: Max. 32mA

Negative logic output

Direction, Clear

Latch: Over 500 µs

Latch

Residual voltage: Max. 1VDC

Max. 1µs (Cable: 2m, I sink = 32mA)

Binary 2 code

Parallel

(A) Photoelectric

(C) Door/Area Sensors

(D) Proximity

(H) Temperature Controllers

(I) SSRs / Power Controllers

(M) Tacho / Speed / Pulse Meters

(N) Display Units

(O) Sensor Controllers (P) Switching Mode Power Supplies

(Q) Stepper Motors

& Drivers & Controllers Logic Panels

X1: Not indicated resolutions are customizable.

SSI Clock Input Frequency 100kHz to 1MHz

- ※2: It calibrates the multi-turn counts by comparing single-turn data before/after power off without counting multi-turn counts when power is off. It shall be used on the condition that no over-rated revolution occurred since proper multi-turn data may not be available if any revolutions occurred over ±90° from the position when power is off.
- X3: OVF alarm is ON when multi-turn count is out of counting range (0 to 8191 revolution).
- It shall be initialized by changing the setting of direction or applying multi-turn count reset or clear signals.
- ※4: Single-turn data shall be initialized as 「0」 when single-turn data reset signal is ON.
- ★5: Multi-turn count shall be initialized as 「0 revolution」 when multi-turn count reset signal is ON.
- ※6: High active is customizable.

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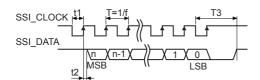
## Specifications

Туре		Ø50mm Multi-turn absolute encoder		
Model		EPM50S8-1013-B-S-24	EPM50S8-1013-B-PN-24	
Electrical specification	Max. Response frequency	/ — 50kHz		
	Power supply	12-24VDC, ±5% (Ripple P-P: Max. 5%)		
	Current consumption	Max. 150mA (Disconnection of the load)  Max. 100mA (Disconnection of the load)		
edif	Insulation resistance	Min. 100MΩ (at 500VDC between all terminals and case)		
g S	Dielectric strength	750VAC 50/60Hz for 1 minute (Between all terminals and case)		
	Connection	Cable type (Cable gland)		
o.g	Starting torque  Moment of inertia  Shaft loading  Max. revolution**7	Max. 40gf·cm (0.004N·m)		
anic	Moment of inertia	Max. 40g·cm² (4×10 <sup>-6</sup> kg·m²)		
ecif	Shaft loading	Radial: 10kgf, Thrust: 2.5kgf		
Ž₫	Max. revolution*7	3000rpm		
Vibration		1.5mm amplitude at frequency of 10 to 55Hz (for 1 min.) in each X, Y, Z direction for 2 hours		
Shock		Approx. Max. 50G		
Environ- Ambient temperature		-10 to 70°C, storage: -25 to 85°C		
ment	Ambient humidity	35 to 85%RH, storage: 35 to 90%RH		
Protection structure		IP64 (IEC standard), Radial cable type: IP50 (IEC standard)		
Cable		Ø6mm, 10-wire, Length: 2m, Shield cable (AWG28, Core diameter: 0.08mm, Number of cores: 19, Insulation out diameter: Ø0.8mm)	Ø6mm, 17-wire×2, Length: 2m, Shield cable (AWG28, Core diameter: 0.08mm, Number of cores: 17, Insulation out diameter: Ø0.8mm)	
Accessory		Mounting bracket, Coupling		
Approval		CE		
Unit weight		Approx. 322g	Approx. 475g	

\*7: Make sure that. Max response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

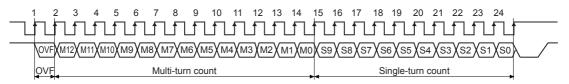
[Max. response revolution (rpm)=  $\frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}]$ \*\*Environment resistance is rated at no freezing or condensation.

## ■ Synchronous Serial Interface (SSI) Output Timing Diagram



Clock Frequency f	100kHz to 1MHz	
_	T: 1 to 10µs	
'	0.5μs < t1 < 5μs	
Time lag t2	t2 < 0.3μs	
Monoflop Time t3	15μs < t3 < 30μs	

## ■ Synchronous Serial Interface (SSI) Data Output

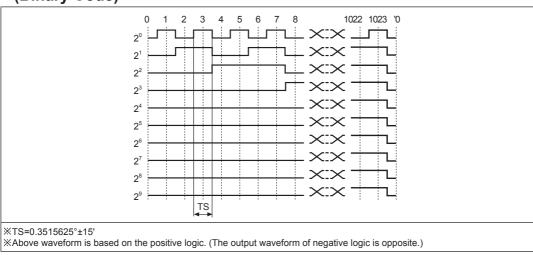


Clock input bit	Data output name	Data output bit	Clock input bit	Data output name	Data output bit
1	Over flow error bit	0 bit	15		9 bit (MSB)
2		12 bit (MSB)	16		8 bit
3		11 bit	17		7 bit
4	Multi-turn count	10 bit	18		6 bit
5		9 bit	19		5 bit
6		8 bit	20		4 bit
7		7 bit	21		3 bit
8		6 bit	22		2 bit
9		5 bit	23		1 bit
10		4 bit	24		0 bit (LSB)
11		3 bit			
12		2 bit			
13		1 bit	1		
14		0 bit (LSB)			

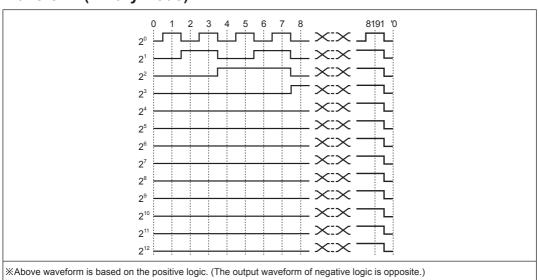
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## Ø50mm Shaft Multi-Turn Absolute Type

# ■ Parallel Interface 1024-Division Single-Turn Data Output Waveform (Binary Code)

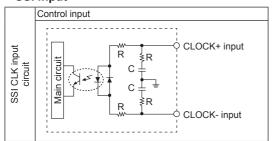


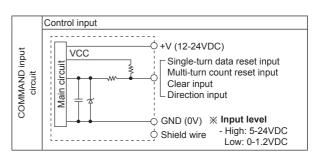
# ■ Parallel Interface 8192 Revolution Multi-Turn Count Data Output Waveform (Binary Code)



## **■** Control Output I/O Circuit

## • SSI input





(A) Photoelectric Sensors

(B) Fiber Optic Sensors

> (C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure

(F) Rotary

(G) Connectors/

(H)

(I) SSRs / Power Controllers

Counters

K) Timers

L) Panel Meters

(M) Tacho / Speed / Pulse Meters

(N) Display Units

> (O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

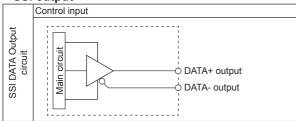
Field Network Devices

(T) Software

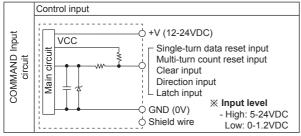
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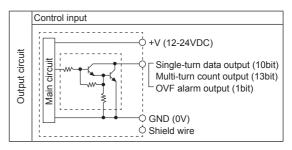
## **■** Control Output I/O Circuit

## SSI output



## Parallel input • output





- XOutput of each bit is the same circuit.
- XOverload or short over specifications may cause circuit break.

## Connections

## • SSI output

Cable			
Cable color	Description	Cable color	Description
Brown	CLOCK+	Gray	Single-turn data reset
Red	CLOCK-	Blue	Multi-turn count reset
Orange	DATA+	Purple	Clear
Yellow	DATA-	Green	Direction
White +V (12-24VDC)			
Black	GND (0V)		
Shield wire	Shield wire Signal shield cable (F.G.)		

## Parallel output

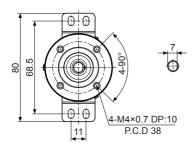
Multi-turn count cable (Sheath color: Black)		
Cable color	Description	
Brown		2º
Red		2 <sup>1</sup>
Orange		2 <sup>2</sup>
Yellow		2 <sup>3</sup>
Green		2 <sup>4</sup>
Blue	Multi turn	2 <sup>5</sup>
Purple	- Multi-turn - count	2 <sup>6</sup>
Gray		27
Pink		2 <sup>8</sup>
Clear	1	2 <sup>9</sup>
Light brown		2 <sup>10</sup>
Light yellow		2 <sup>11</sup>
Light green		2 <sup>12</sup>
Light blue OVF		
Light purple	Multi-turn count reset	
White +V (12-24VDC)		
Black	ack GND (0V)	
Shield wire Signal shield cable (F.G.)		G.)

Single-turn data cable (Sheath color: Gray)		
Cable color	Description	
Brown		2 <sup>0</sup>
Red		2 <sup>1</sup>
Orange		2 <sup>2</sup>
Yellow		2 <sup>3</sup>
Green	Single-turn	24
Blue	data	2 <sup>5</sup>
Purple		2 <sup>6</sup>
Gray		2 <sup>7</sup>
Pink		2 <sup>8</sup>
Clear		2 <sup>9</sup>
Light brown	NC	
Light yellow	Direction	
Light green	Latch	
Light blue	Clear	
Light purple Single-turn data reset		
White	+V (12-24VDC)	
Black	GND (0V)	
Shield wire	rire Signal shield cable (F.G.)	

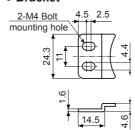
- XPlease be cautious not to wire wrongly.
- \*\*As for parallel output, it is recommended to connect +V and GND of both multi-turn count cable and single-turn data cable.
- XThe metal case and shield wire of encoder should be grounded (F.G.).
- \*Input/Output cable must not be short-circuited, because Driver IC is used in output circuit.

## Ø50mm Shaft Multi-Turn Absolute Type

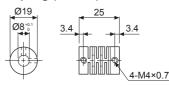
## Dimensions



#### Bracket



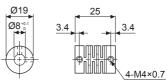
#### • Coupling (EPM50)



- Parallel misalignment: Max. 0.25mm
- Angular misalignment: Max. 5°
- End-play: Max. 0.5mm

XFor parallel misalignment, angular

XFor flexible coupling (ERB Series)



(unit: mm)

misalignment, end-play terms, refer to the

information, refer to the F-64.

(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity

(I) SSRs / Power Controllers

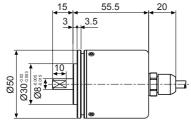
(N) Display Units

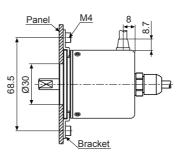
(P) Switching Mode Powe Supplies

(Q) Stepper Motors

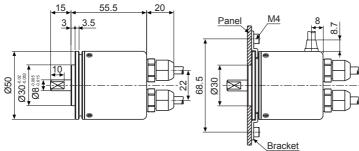
(R) Graphic/ Logic Panels

## SSI output





## Parallel output



## Functions

## O Single-turn data reset

Single-turn data will be initialized to 「0」 when GND (low level) signal is applied over 100ms on single-turn data reset line. In case of not using single-turn data reset line, connect the line to OPEN or +V (High level).

#### Multi-turn count reset

Multi-turn data will be initialized to Frevolution 0 , when GND (Low level) signal is applied over 100ms on multicount reset line. In case of not using multi-turn count reset line, connect the line to OPEN or + V (High level). When OVF alarm occurs, OVF alarm will also be initialized if multi-turn count reset input signal is applied.

## O Clear

Single-turn data will be initialized to \[ \Gamma\_{\textstyle \textstyle \tex will be also initialized to revolution 0 when GND (Low level) signal is applied over 100ms on Clear line. In case of not using clear line, connect the line to OPEN or + V (High level). When OVF alarm occurs, OVF alarm will be initialized with clear input.

#### O Direction

Connect Direction line to OPEN or +V (High level) and turn on the power. Output will increase when rotation direction is CW from shaft axis. In case of connecting to GND (Low level), output will increase when rotation direction is CCW. If direction setting is reset, single-turn data, multi-turn count and OVF will be reset together since direction setting is initial setting which is set with Power ON.

## Latch (Parallel output model only)

When connecting latch line to GND (Low level) over 500 µs, outputs for single-turn data, multi-turn count and OVF at latch point will remain. When latch line is connected to OPEN or +V (High level), output will returned to operating mode output.

## Overflow alarm (OVF)

It is an alarm function providing output when multi-turn count is out of rotation ranges (0 to 8191 revolutions). OVF will be initialized through direction setting change, multiturn count reset or clear input.

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